Type 3374 Electric Actuator



Application

Electric actuator for plant engineering and HVAC



The actuator is a linear actuator with or without fail-safe action available either in a version with a three-step signal or a version with digital positioner. It can be combined with SAMSON Series V2001 and Series 240 Valves as well as Type 3260 and Type 3214 Valves.

Special features

- Actuator optionally available with either integrated yoke (Fig. 1) or using an M30 x 1.5 ring nut (Fig. 2) including the necessary stem connecting parts
- Actuator with fail-action "actuator stem extends" tested by the German Technical Inspectorate (TÜV) according to DIN EN 14597 in combination with various SAMSON valves
- Motor switched off by torque-dependent limit contacts
- Mechanical override ¹⁾
- Thrust up to 2.5 kN
- No maintenance required

Three-step version

- Power supply:
 - 230 V/24 V with 50/60 Hz or
 - 120 V/60 Hz
- Synchronous motor with maintenance-free planetary gear
- Additional electrical equipment:
 - Mechanical limit contacts
 - Resistance transmitters

Version with digital positioner

- Power supply:
 - 24 V with 47 to 63 Hz and DC
 - 85 to 264 V with 47 to 63 Hz
- Stepper motor with maintenance-free planetary gear
- All function settings performed using a rotary pushbutton on the actuator
- Backlit LCD
- Additional electrical equipment:
 - Mechanical limit contacts
 - Electronic limit contacts
 - RS-485 module for Modbus-RTU communication
- Settings performed in TROVIS-VIEW
- Not in versions with positioner and fail-safe action



Principle of operation

The electric actuator consists of a reversible motor and a maintenance-free planetary gear with ball screw drive. The motor is switched off by torque-dependent limit contacts or in case of overload.

Actuators with an integrated yoke (Fig. 5a) are primarily combined with the following valves:

- V2001
- Type 3260 in DN 65 to 150
- Type 3214 in DN 65 to 100
- Type 3214 balanced by a diaphragm, DN 125 to 250

Actuators with central attachment are primarily combined with valves that have their own yoke:

Series 240 (Fig. 5b)

 Type 3214 balanced by a bellows, DN 125 to 250 (Fig. 5c)

Fail-safe action

The Type 3374 Electric Actuator is available optionally with fail-safe action:

Actuator stem extends: Upon power supply failure, the actuator stem extends

Actuator stem retracts: Upon power supply failure, the actuator stem retracts

Additional electrical equipment

Mechanical limit contacts

The mechanical limit contacts can be adjusted independently from one another. They are actuated by continuously adjustable cam disks.

Electronic limit contacts

The electronic limit contacts consist of relays with changeover contacts. In contrast to the mechanical limit contacts, the electronic limit contacts no longer function after a power supply failure. The relays are de-energized and the contacts change to the idle state.

Resistance transmitters

The resistance transmitter is linked to the gear and produces a resistance signal between approx. 0 and 1000 Ω (usable range 0 to 800 Ω) proportional to the valve travel.

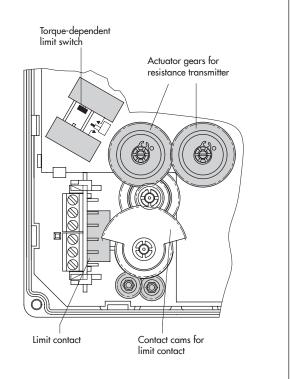
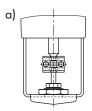
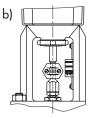
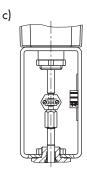


Fig. 4: Partial view with opened cover







With integrated yoke for

a) Series V2001, Type 3260 (DN 65 to 150)
 Type 3214 (DN 65 to 100)

With central attachment for

- b) Series 240
- c) Type 3214 (DN 125 to 250) Series 240 (Type 3241 and Type 3244)

Fig. 5: Attachment to various valves

1. Three-step version

Table 1: Technical data

Туре 3374		-10	-11	-15	-21	-26	-31	-36
Version with		Yo	ke	Ring nut	Yoke	Ring nut	Yoke	Ring nut
Fail-safe action		Without Extends Re		Ret	racts			
Rated travel	mm	30 15 30 15		5				
Transit time for rated	travel							
Standard	s	240	120	240		1:	20	
Fast	s	120	60	120		6	50	
In the event of fail-s action	afe s	- 12						
Stroking speed								
Standard	mm/s				0.125			
Fast	mm/s				0.25			
In the event of fail- safe action	mm/s		_			1.	25	
Thrust	Retracts		2.5 kN			0.5	5 kN	
	Extends		2.5 kN			2	kN	
		230 V (+10/-15 %), 60 Hz 24 V (+10/-15 %), 50 Hz 24 V (+10/-15 %), 60 Hz 120 V (90 to 132 V), 60 Hz						
Power consumption VA		7.5/13 ²⁾ 10.5/16 ²⁾						
Motor switch-off		Torque-dependent						
Degree of protection		IP 54 according to EN 60529, IP 65 with cable glands (can be retrofitted) 1) Suspended mounting not permitted						
Overvoltage category	у	II according to EN 60664						
Design and testing		According to EN 61010						
Class of protection		II according to EN 61140						
Noise immunity		According to EN 61000-6-2, EN 61326						
Noise emission		According to EN 61000-6-3, EN 61326						
Manual override		Hex wrench · Adjustment not possible after fail-safe action has been triggered.						
Weight kg	(approx.)	3	.2	3.3	3.9	4.0	3.5	3.6
Materials			Housing and cover: Plastic (glass-fiber reinforced PPO)					
Additional electrical	equipment							
Limit contacts		Two travel-dependent, adjustable changeover switches, max. 250 V AC, 1 A						
Resistance transmitters		0 to 1000 Ω, (0 to 900 Ω at rated travel) max. permissible current 1 mA						

Cable glands M20 x 1.5 with metal nut SW 23/24 (order no. 1400-8828) Actuator with faster motor

2. Version with digital positioner

Table 2: Technical data · Without fail-safe action

Туре 3374		-10	-11	-15			
Type of connection		With yoke		With ring nut			
Travel mm 30		30	15	30			
Travel limitati	ion	В	Between 10 and 100 % of the rated travel				
Manual over	ride		4 mm hex wrench				
Electrical con	nection						
Power supply	,	24 V	(±15 %), 47 to 63 Hz and 24 V DC (±1	5 %)			
			85 to 264 V, 47 to 63 Hz				
Power consu	mption		Speed level: Normal · Fast				
24 V	AC	12.5 VA · 16.5 VA					
Z4 V	DC	7.5 W · 11 W					
85 to 264 V	AC	13.8 to 20 VA					
Transit time i	n s · Stroking	speed in mm/s					
Standard	Standard	120 · 0.25	60 · 0.25	120 · 0.25			
version	Fast	60 · 0.5	30 · 0.5	60 · 0.5			
Actuator	Standard	60 · 0.5	30 · 0.5	60 · 0.5			
with faster motor	Fast	30 · 1.0	15 · 1.0	30 · 1.0			
Thrusts in kN (Standard version · Version with faster motor)							
Extends 2.5 · 1.25		2.5 · 1.25	2.5 · 1.25				
Retracts 2.5 · 1.25		2.5 · 1.25	2.5 · 1.25				
Weight							
	kg (approx.)	3.5	3.5	3.6			

Table 3: Technical data · With fail-safe action

Actuator	Туре 3374	-21	-26	-31	-36		
Type of con	nection	With yoke	With ring nut	With yoke	With ring nut		
Fail-safe ac	tion	Extends		Ret	racts		
Travel	mm		15	1	5		
Travel limit	ation		Between 10 and 100	0 % of the rated travel			
Manual ove	erride						
Electrical co	onnection						
Power supp	oly		24 V (±15 %), 47 to 63	Hz and 24 V DC (±15 %)			
			85 to 264 V	, 47 to 63 Hz			
Power cons	sumption		Speed level:	Normal · Fast			
24 V	AC	18 VA · 23 VA					
DC DC			11.5 W ·15 W				
85 to 264	V AC	19.8 to 26 VA					
Transit time	e in s · Stroking	speed in mm/s					
Standard		60 · 0.25	60 · 0.25	60 · 0.25	60 · 0.25		
Fast		30 · 0.5	30 · 0.5	30 · 0.5	30 · 0.5		
Upon fail-s	afe action	12 · 1.25	12 · 1.25	12 · 1.25	12 · 1.25		
Thrusts in k	κN						
Thrust (stem	n extends)	2	2	2	2		
Thrust (stem	retracts)	0.5	0.5	0.5	0.5		
Nominal th	rust of safety	2	2	0.5	0.5		
Weight	,						
	kg (approx.)	4.2	4.3	3.8	3.9		

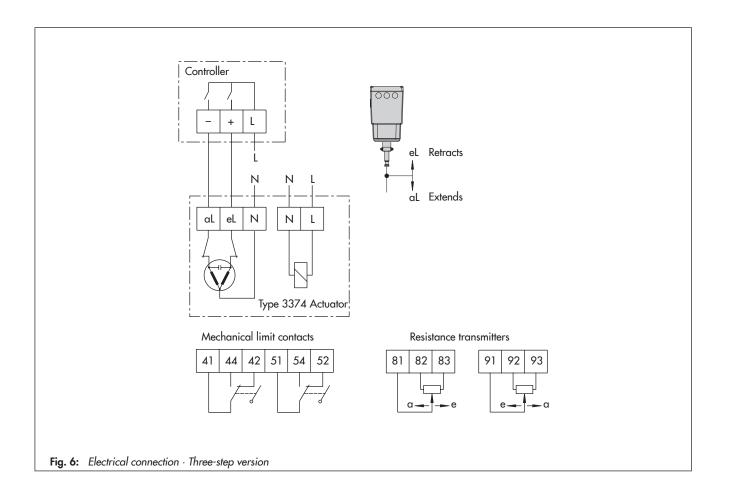
Table 4: Common technical data

Туре 3374-хх				
Input signal	Current input	$0/4$ to 20 mA, adjustable \cdot R _i = 50 Ω		
inpui signai	Voltage input	$0/2$ to 10 V, adjustable · $R_i = 30 \text{ k}\Omega$		
	Pt 1000 input	Measuring range: –50 to 150 °C, 300 μA		
	· ·			
Binary input		By bridging the terminals, not galvanically isolated		
Position feedback	Current Resolution	0/4 to 20 mA, adjustable · Error message 24 mA		
		1000 steps or 0.02 mA Max. 200 Ω		
	Load			
	Voltage Resolution	0/2 to 10 V, adjustable · Error message 12 V		
	Load	1000 steps or 0.01 V Minimum 5 kΩ		
Binary input	Loud	Open-circuit voltage: 10 V; short-circuit current: 5 mA By bridging the terminals, not galvanically isolated		
Binary output		Floating, max. 230 V AC/1 A		
Applications	Positioner	The travel follows the input signal		
, .ppcacc	PID controller	Fixed set point control		
	Two-step mode	Two-step behavior, control over binary input		
	Three-step mode 1)	Three-step behavior, control over binary input		
Temperature closed-loop control upon input signal failure 1)		The integrated PID controller uses a fixed set point for closed-loop control when the input signal is missing.		
Display		Icons for functions, codes and text field with backlight		
Rotary pushbutton		Operating control for on-site operation to select and confirm codes and values		
Interface	Standard	RS-232 · For point-to-point connection to communication participants or for memory pen · Permanently installed · Connection: RJ-12 connector socket		
Motor switch-off		By torque-dependent limit contacts		
Degree of protection	on acc. to EN 60529	IP 54 with cable entries, IP 65 with cable glands (can be retrofitted) ²⁾ Suspended mounting not permitted according to EN 60664		
Overvoltage catego	ory	Il according to EN 61010		
Design and testing		According to EN 61010		
Class of protection		II according to EN 61140		
EMC		According to EN 61000-6-2, EN 61000-6-3 and EN 61326		
Degree of contamir	nation	2 according to EN 61010		
Noise immunity		According to EN 61000-6-2		
Noise emission		According to EN 61000-6-3		
Mechanical enviror	nmental conditions	Class 1M2 according to EN 60721-3-1:1998		
		Class 2M1 according to EN 60721-3-2:1998		
		Class 3M4 according to EN 60721-3-3:1998		
		Class 4M4 according to EN 60721-3-4:1998		
Ambient 2		5 to 60 °C		
Permissible temperatures 3) Storage		-25 to +70 °C		
Humidity		5 to 95 % relative humidity, no dew formation		
Compliance		C € · EH[
Additional electrica	al equipment			
Limit contacts	Mechanical	Two adjustable limit contacts with changeover switches; 230 V AC/1 A · Without contact protection		
	Electronic	Two adjustable limit contacts with relay and changeover switches; 230 V AC/1 A · Without contact protection		
RS-485 module (ord	der no. 1402-1522)	Module for Modbus-RTU communication		

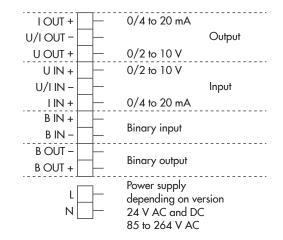
Application only available in Type 3374, revision 3

Cable glands M20 x 1.5 with metal nut SW 23/24 (order no. 1400-8828)

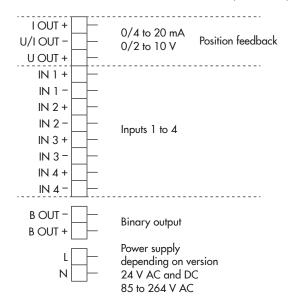
The permissible medium temperature depends on the valve on which the electric actuator is mounted. The limits in the valve documentation apply.



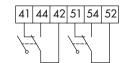
For actuators with firmware version 2.xx (revision 2)



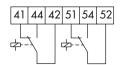
For actuators with firmware version 3.xx (revision 3)



Mechanical limit contacts



Electronic limit contacts



Depending on the selected application, connect the wires to the terminals as follows:

Positioner:

Input	Terminal
Current: 0/4 to 20 mA	IN 1 +/IN 1 -
Voltage: 0/2 to 10 V	IN 2 +/IN 2 -
Binary signal	IN 4 +/IN 4 -

Three-step mode:

Input	Terminal	
Thr	ee step sig	nal:
Retracts Extends		IN 2 + IN 2 - IN 3 + IN 3 -
Binary signal	IN 4 +/IN 4 -	

PID Controller and Temperature closed-loop control upon input signal failure

Input	Terminal
Current: 0/4 to 20 mA	IN 1 +/IN 1 -
Voltage: 0/2 to 10 V	IN 2 +/IN 2 -
Pt 1000	IN 3 +/IN 3 -
Binary signal	IN 4 +/IN 4 -

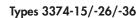
Two-step mode:

Input	Terminal	
Open-closed	IN 2 +/IN 2 -	
Binary signal	IN 4 +/IN 4 -	

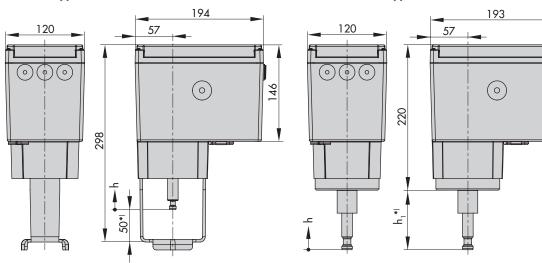
Fig. 7: Electrical connection · Version with digital positioner

Dimensions in mm

Type 3374-10/-11/-21/-31



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*) When actuator stem is fully extended

Туре 3374	Dimension h	Dimension h ₁	
-10	30	_	
-11	15	_	
-21	15	_	
-31	15	_	
-15	30	90	
-26	15	75	
-36	15	75	

Ordering text · Three-step version

Electric actuator Type 3374- ... Rated travel 15/30 mm

Version with fail-safe action Actuator stem extends or re-

tracts only with 15 mm travel

Power supply 230 V/50 or 60 Hz,

24 V/50 or 60 Hz or

120 V/60 Hz

Additional electrical equipment

Two mechanical limit contacts

Two resistance transmitters 0 to 1000Ω

Ordering text · Version with digital positioner

Electric actuator Type 3374- ...
Rated travel 15/30 mm

Version with fail-safe

action With/without

Gear version Standard or actuator with faster

motor

Power supply 24 V, 50/60 Hz and DC

85 to 264 V, 50/60 Hz

Additional electrical equipment

Two limit contacts Mechanical/electronic

List of documentation

Mounting and operating instructions

- for Type 3374, revision 2: ► EB 8331-4 (rev. 2)

for Type 3374, revision 3: ► EB 8331-4 (rev. 3)

Specifications subject to change without notice



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